

**stichting  
mathematisch  
centrum**



---

AFDELING MATHEMATISCHE BESLISKUNDE  
(DEPARTMENT OF OPERATIONS RESEARCH)

BW 12B/80

AUGUSTUS

K.R. BAKER, E.L. LAWLER, J.K. LENSTRA, A.H.G. RINNOOY KAN

PREEMPTIVE SCHEDULING OF A SINGLE MACHINE TO MINIMIZE MAXIMUM  
COST SUBJECT TO RELEASE DATES AND PRECEDENCE CONSTRAINTS

Preprint

---

**kruislaan 413 1098 SJ amsterdam**

BIBLIOTHEEK MATHEMATISCH CENTRUM  
—AMSTERDAM—

*Printed at the Mathematical Centre, 413 Kruislaan, Amsterdam.*

*The Mathematical Centre, founded the 11-th of February 1946, is a non-profit institution aiming at the promotion of pure mathematics and its applications. It is sponsored by the Netherlands Government through the Netherlands Organization for the Advancement of Pure Research (Z.W.O.).*

PREEMPTIVE SCHEDULING OF A SINGLE MACHINE TO MINIMIZE MAXIMUM COST  
SUBJECT TO RELEASE DATES AND PRECEDENCE CONSTRAINTS

K.R. BAKER

*Dartmouth College, Hanover, New Hampshire*

E.L. LAWLER

*University of California, Berkeley*

J.K. LENSTRA

*Mathematisch Centrum, Amsterdam*

A.H.G. RINNOOY KAN

*Erasmus University, Rotterdam*

ABSTRACT

Suppose  $n$  jobs are to be processed on a single machine, subject to release dates and precedence constraints. The problem is to find a preemptive schedule which minimizes the maximum job completion cost. We present an  $O(n^2)$  algorithm for this problem, generalizing previous results of the second author.

KEY WORDS & PHRASES: *preemptive scheduling, single machine, release dates, precedence constraints, maximum cost, polynomial algorithm.*

NOTE: This report will be submitted for publication in a journal.

## 1. INTRODUCTION

We consider the problem of finding a preemptive schedule for  $n$  jobs on a single machine which minimizes the maximum job completion cost subject to given release dates and precedence constraints.

More specifically, suppose that  $n$  jobs  $1, \dots, n$  are to be processed on a single machine which can execute at most one job at a time. Each job  $j$  becomes available at its release date  $r_j$  and requires a processing time  $p_j$ . Moreover, a precedence relation  $\rightarrow$  between the jobs is given; if  $j \rightarrow k$ , it is required that job  $j$  be completed before job  $k$  can start. Unlimited preemption is allowed, i.e., the execution of any job may arbitrarily often be interrupted and resumed at a later time. Associated with each job  $j$  is a monotone nondecreasing cost function  $f_j$ ; if job  $j$  has a completion time  $C_j$ , a cost  $f_j(C_j)$  is incurred. We assume that each  $f_j$  can be evaluated in unit time for any value of the argument. The problem is to find a feasible schedule such that the maximum cost  $f_{\max} = \max_j \{f_j(C_j)\}$  is minimized.

If all release dates are equal, there is no advantage to preemption, and the problem is solvable in  $O(n^2)$  time [4]. In Section 2, we recall this algorithm and give an alternative proof of its correctness.

If the release dates may be arbitrary, the preemptive case is still solvable in  $O(n^2)$  time. In Sections 3 and 4, we present an algorithm for this case by extending the approach of Section 2; Section 5 contains a numerical example. We note that the nonpreemptive case is NP-hard in the strong sense, even without precedence constraints [1;5].

In the notation of [2],  $1|prec|f_{\max}$  is considered in Section 2,  $1|pmtn, r_j|f_{\max}$  in Section 3 and  $1|pmtn, prec, r_j|f_{\max}$  in Section 4;  $1|r_j|f_{\max}$  is unary NP-hard.

## 2. EQUAL RELEASE DATES

We first assume that all release dates are equal to 0, in which case we need only consider schedules without preemption and without machine idle time.

Let  $N = \{1, \dots, n\}$  be the set of all jobs, let  $N' \subseteq N$  be the set of jobs without successors, and for any  $S \subseteq N$  define

$$p(S) = \sum_{j \in S} p_j;$$

$f_{\max}(S)$  = value of  $f_{\max}$  in a given schedule for the jobs in  $S$ ;

$f_{\max}^*(S)$  = value of  $f_{\max}$  in an optimal schedule for the jobs in  $S$ .

Clearly,  $f_{\max}^*(N)$  satisfies the following two inequalities:

$$f_{\max}^*(N) \geq \min_{j \in N} \{f_j(p(N))\};$$

$$f_{\max}^*(N) \geq \max_{j \in N} \{f_{\max}^*(N - \{j\})\}.$$

Let job  $\ell \in N$  be such that

$$f_{\ell}(p(N)) = \min_{j \in N} \{f_j(p(N))\}.$$

Consider a schedule which is optimal subject to the condition that job  $\ell$  is processed *last*. For any such schedule, we have

$$f_{\max}(N) = \max\{f_{\ell}(p(N)), f_{\max}^*(N - \{\ell\})\} \leq f_{\max}^*(N).$$

It follows that there exists an optimal schedule in which job  $\ell$  is in the last position.

By repeated application of this rule, one obtains an optimal schedule in  $O(n^2)$  time. The above correctness proof differs from the one given in [4] in that it does not rely on an interchange argument.

### 3. ARBITRARY RELEASE DATES, NO PRECEDENCE CONSTRAINTS

We now consider the case in which arbitrary release dates are specified. First, we assume that there are no precedence constraints.

Our first observation is that, since preemption is allowed, it is never advantageous to leave the machine idle when unscheduled jobs are available. Hence, the time at which all jobs will be completed can be determined in advance by scheduling the jobs in order of nondecreasing  $r_j$ . This schedule naturally decomposes into *blocks*, where a block  $B \subseteq N$  is defined as a minimal set of jobs processed without idle time from  $r(B) = \min_{j \in B} \{r_j\}$  until  $t(B) = r(B) + p(B)$ , such that each job  $j \notin B$  is either completed not later

than  $r(B)$  ( $C_j \leq r(B)$ ) or not released before  $t(B)$  ( $r_j \geq t(B)$ ).

It is easily seen that, in minimizing  $f_{\max}$ , we can consider each block  $B$  separately. As in Section 2,  $f_{\max}^*(B)$  satisfies the following two inequalities:

$$\begin{aligned} f_{\max}^*(B) &\geq \min_{j \in B} \{f_j(t(B))\}; \\ f_{\max}^*(B) &\geq \max_{j \in B} \{f_{\max}^*(B - \{j\})\}. \end{aligned}$$

Let job  $\ell \in B$  be such that

$$(*) \quad f_{\ell}(t(B)) = \min_{j \in B} \{f_j(t(B))\}.$$

Consider a schedule for block  $B$  which is optimal subject to the condition that job  $\ell$  is processed *only if no other job is available*. It consists of two complementary parts:

- (i) an optimal schedule for the set  $B - \{\ell\}$ , which decomposes into a number of subblocks  $B_1, \dots, B_b$  with respect to this job set;
- (ii) a schedule for job  $\ell$ , which is given by  $[r(B), t(B)] - \bigcup_{i=1}^b [r(B_i), t(B_i)]$ ; note that job  $\ell$  is completed at time  $t(B)$ .

For any such schedule, we have

$$f_{\max}(B) = \max\{f_{\ell}(t(B)), f_{\max}^*(B - \{\ell\})\} \leq f_{\max}^*(B).$$

It follows that there exists an optimal schedule in which job  $\ell$  is scheduled as prescribed above.

The problem can now be solved in the following way. First, order the jobs according to nondecreasing  $r_j$  in  $O(n \log n)$  time. Next, determine the initial block structure by scheduling the jobs in order of nondecreasing  $r_j$ ; this requires  $O(n)$  time. For each block  $B$ , select job  $\ell \in B$  subject to  $(*)$ , determine the block structure of the set  $B - \{\ell\}$  by scheduling the jobs in this set in order of nondecreasing  $r_j$ , and construct the schedule for job  $\ell$  as given above; all this requires  $O(|B|)$  time. By repeated application of this procedure to each of the subblocks, one obtains an optimal schedule in  $O(n^2)$  time.

The algorithm generates at most  $n-1$  preemptions. This is easily proved by induction. It is obviously true for  $n = 1$ . Suppose it is true for blocks of size smaller than  $|B|$ . The schedule for block  $B$  contains at most  $|B_i| - 1$

preemptions for each subblock  $B_i$  ( $i = 1, \dots, b$ ) and at most  $b$  preemptions for the selected job  $\ell$ , so that the total number of preemptions is no more than  $\sum_{i=1}^b (|B_i| - 1) + b = |B| - 1$ .

We note that the use of preemption is essential for our algorithm. If no preemption is allowed, it is not possible to determine the block structure of an optimal schedule in advance.

#### 4. ARBITRARY RELEASE DATES, ARBITRARY PRECEDENCE CONSTRAINTS

We next consider the case in which arbitrary precedence constraints are specified. The algorithm can be extended to solve this more general problem as well.

First, the release dates are modified such that  $r_j + p_j \leq r_k$  whenever  $j \rightarrow k$ . This implies that, in constructing the blocks, one can ignore the precedence constraints. The modification requires  $O(n^2)$  time: renumber the jobs in topological order (i.e., such that if  $j \rightarrow k$  then  $j < k$ ) and set  $r_k = \max\{r_k, \max\{r_j + p_j \mid j \rightarrow k\}\}$  for  $k = 2, \dots, n$  (cf. [3]). After this, the jobs are ordered according to nondecreasing  $r_j$  in  $O(n \log n)$  time.

Secondly, suppose that for each job  $j$  belonging to a block  $B$  its outdegree  $d_j$  with respect to  $B$ , i.e. the number of jobs  $k \in B$  such that  $j \rightarrow k$ , is known. For each block  $B$ , the set  $B' = \{j \mid j \in B, d_j = 0\}$  of jobs without successors in  $B$  is determined, and the selection of job  $\ell \in B$  subject to (\*) is replaced by the selection of job  $\ell \in B'$  such that

$$f_\ell(t(B)) = \min_{j \in B'} \{f_j(t(B))\}.$$

This insures that the selected job  $\ell$  has no successors within the block  $B$ .

As to the implementation of this procedure, let us suppose that the precedence constraints are represented simply by a job adjacency matrix and the blocks by lists of jobs in order of nondecreasing  $r_j$ . Initially, for each job  $j$  the number  $d_j$  of jobs  $k$  such that  $j \rightarrow k$  is recorded. The computation of all  $d_j$  requires  $O(n^2)$  time. After construction of the initial blocks  $B_1, \dots, B_b$ , the outdegrees are updated: consider each  $B_i$  ( $i = 1, \dots, b-1$ ) in succession and decrease  $d_j$  by 1 for each pair  $(j, k)$  such that  $j \in B_i$ ,

$k \in \bigcup_{h=i+1}^b B_h$  and  $j \rightarrow k$ . For each block  $B$ , after construction of the subblocks  $B_1, \dots, B_b$  of the set  $B - \{\ell\}$  and of the schedule for job  $\ell$ , the outdegrees are updated again: consider each  $B_i$  ( $i = 1, \dots, b$ ) in succession and decrease  $d_j$  by 1 for each pair  $(j, k)$  such that  $j \in B_i$ ,  $k \in (\bigcup_{h=i+1}^b B_h) \cup \{\ell\}$  and  $j \rightarrow k$ . All updates of the  $d_j$  together require  $O(n^2)$  time, since each entry of the adjacency matrix is inspected at most once. Further, each  $B'$  is determined in  $O(|B|)$  time. It follows that one still obtains an optimal schedule in  $O(n^2)$  time.

## 5. NUMERICAL EXAMPLE

Finally, we illustrate our algorithm with a numerical example. Suppose there are five jobs, with release dates and processing times as given in Table 1(a), precedence constraints as specified in Figure 1, and cost functions as depicted in Figure 2.

The modified release dates and the initial outdegrees are given in Table 1(b). By scheduling the jobs in order of increasing  $r_j$ , we obtain two blocks:  $B_1 = \{1, 2, 3, 4\}$  from 0 until 12 and  $B_2 = \{5\}$  from 14 until 18 (Figure 3(a)). We update the outdegrees of the jobs in  $B_1$  as indicated in Table 1(c).

Block  $B_2$  consists of a single job and therefore represents an optimal part of the schedule. For block  $B_1$  we find  $B'_1 = \{3, 4\}$  and select job 3 since  $f_3(12) < f_4(12)$ . By rescheduling the jobs in  $B_1$  while processing job 3 only if no other job is available, we obtain two subblocks:  $B_{11} = \{1, 2\}$  from 0

	job	j	1	2	3	4	5
(a)	release date	$r_j$	0	2	0	8	14
	processing time	$p_j$	4	2	4	2	4
(b)	modified release date	$r_j$	0	2	4	8	14
	outdegree	$d_j$	1	2	1	0	0
(c)	updated outdegree	$d_j$	1	2	0	0	
(d)	updated outdegree	$d_j$	0	0		0	

Table 1. Parameters for the example.



until 6 and  $B_{12} = \{4\}$  from 8 until 10 (Figure 3(b)). We update the outdegrees of the jobs in  $B_{11}$  and  $B_{12}$  as indicated in Table 1(d).

Block  $B_{12}$  needs no further attention. For block  $B_{11}$  we find  $B'_{11} = \{1, 2\}$  and select job 1 since  $f_1(6) < f_2(6)$ . By rescheduling the jobs in  $B_{11}$  again, we finally obtain an optimal schedule (Figure 3(c)).

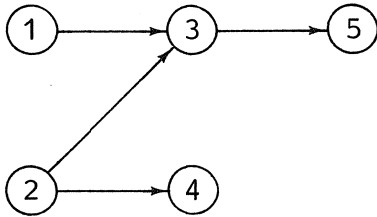


Figure 1. Precedence constraints for the example.

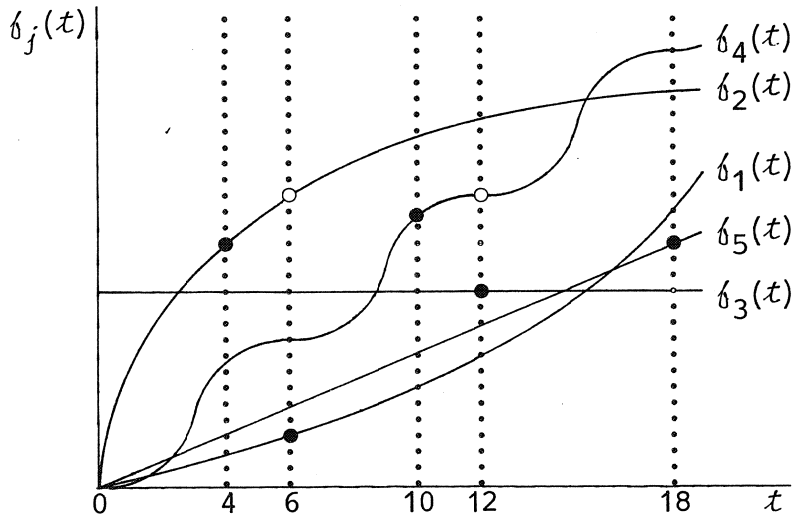
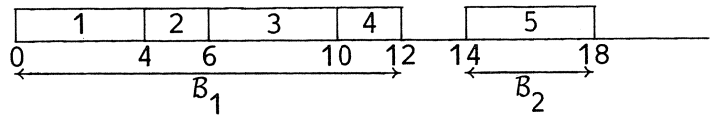
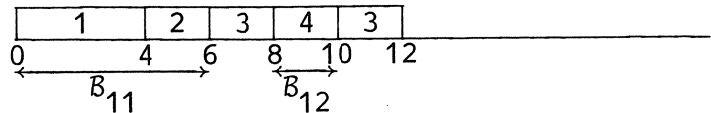


Figure 2. Cost functions for the example.

(a) Initial schedule



(b) New schedule for block  $B_1$



(c) Optimal schedule

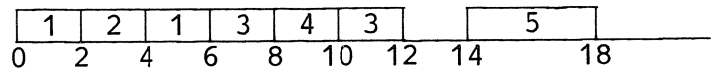


Figure 3. Schedules for the example.

## ACKNOWLEDGMENTS

The authors gratefully acknowledge the useful comments from C.U. Martel. This research was partially supported by NSF Grant MCS78-20054.

## REFERENCES

1. M.R. GAREY, D.S. JOHNSON (1977) Two-processor scheduling with start-times and deadlines. *SIAM J. Comput.* 6, 416-426.
2. R.L. GRAHAM, E.L. LAWLER, J.K. LENSTRA, A.H.G. RINNOOY KAN (1979) Optimization and approximation in deterministic sequencing and scheduling: a survey. *Ann. Discrete Math.* 5, 287-326.
3. B.J. LAGEWEG, J.K. LENSTRA, A.H.G. RINNOOY KAN (1976) Minimizing maximum lateness on one machine: computational experience and some applications. *Statistica Neerlandica* 30, 25-41.
4. E.L. LAWLER (1973) Optimal sequencing of a single machine subject to precedence constraints. *Management Sci.* 19, 544-546.
5. J.K. LENSTRA, A.H.G. RINNOOY KAN, P. BRUCKER (1977) Complexity of machine scheduling problems. *Ann. Discrete Math.* 1, 343-362.